50 mm Diameter Incremental Rotary Encoders

E50 Series

INSTRUCTION MANUAL

TCD210020AD

Autonics

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

Follow Autonics website for the latest information.

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- A symbol indicates caution due to special circumstances in which hazards may occur.

★ Warning Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.) ailure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
- re to follow this instruction may result in explosion or fire.

03. Install on a device panel to use. Failure to follow this instruction may result in fire.

- 04. Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire.
- 05. Check 'Connections' before wiring.
- ailure to follow this instruction may result in fire 06. Do not disassemble or modify the unit.

Failure to follow this instruction may result in fire

▲ Caution Failure to follow instructions may result in injury or product damage.

- 01. Use the unit within the rated specifications.
- ailure to follow this instruction may result in fire or product damage.
- 02. Do not short the load.
- ailure to follow this instruction may result in fire
- 03. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists.

Failure to follow this instruction may result in product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'.
- Otherwise, It may cause unexpected accidents
- 5 VDC==, 12 24 VDC== power supply should be insulated and limited voltage / current or Class 2, SELV power supply device.
- · For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- Ground the shield wire to the F.G. terminal.

 When supplying power with SMPS, ground the F.G. terminal and connect the noise canceling capacitor between the 0 V and F.G. terminals.
- Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- For Line driver unit, use the twisted pair wire which is attached seal and use the receiver for RS-422A communication.
- Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc. by line resistance or capacity between lines.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications') - Altitude max. 2,000 m
- Pollution degree 2
- Installation category II

Cautions during Installation

- Install the unit correctly with the usage environment, location, and the designated specifications.
- Do not load overweight on the shaft.
- Do not put strong impact when insert a coupling into shaft.
- Failure to follow this instruction may result in product damage. \bullet When fixing the product or coupling with a wrench, tighten under 0.15 N m.
- If the coupling error (parallel misalignment, angular misalignment) between the shaft increases while installation, the life cycle of the coupling and the encoder can be
- Do not apply tensile strength over 30 N to the cable.

Ordering Information

Shaft outer diameter

This is only for reference, the actual product does not support all combinations.

For selecting the specified model, follow the Autonics website.											
E50	0	0	-	8	-	4	-	6	- 6	-	0
Shaft type Gontrol output											
S: Shaft type					T: Totem pole output						
A Chaft autor diameter					N: NPN open collector output						

V: Voltage output

1: Line driver output

Resolution O Power supply

Number: Refer to resolution in $5:5 \text{ VDC} = \pm 5\%$ 24· 12 - 24 VDC == + 5% 'Specifications

Output phase Connection No mark: Axial cable type 2: A. B 3: A, B, Z C: Axial cable connector type CR: Axial connector type $4: A, \overline{A}, B, \overline{B}$ 6: A, \overline{A} , B, \overline{B} , Z, \overline{Z} CS: Radial connector type

Product Components

 Product • Bolt \times 7 Instruction manual • Coupling \times 1 $\bullet \; \mathsf{Bracket} \times 1$

Sold Separately

• M17 connector cable: CID6S-□, CID9S-□

Connections

- Unused wires must be insulated.
- The metal case and shield cable of encoders must be grounded (F.G.).
- F.G. (Frame Ground) must be grounded separately

■ Totem pole / NPN open collector / Voltage output

Pin	Color	Function	Pin	Color	Function
1	Black	OUTA	4	Brown	+V
2	White	OUTB	5	Blue	GND
3	Orange	OUTZ	6	Shield	F.G.



■ Line driver output

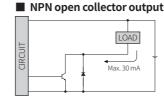
Pin	Color	Function	Pin	Color	Function
1	Black	OUTA	5	White	OUT B
2	Red	OUTĀ	6	Gray	OUT B
3	Brown	+V	7	Orange	OUTZ
4	Blue	GND	8	Yellow	OUT Z
_			9	Shield	F.G.

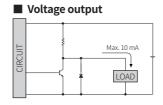


Inner Circuit

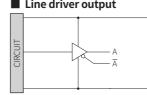
Output circuits are identical for all output phase.

■ Totem pole output





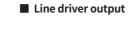


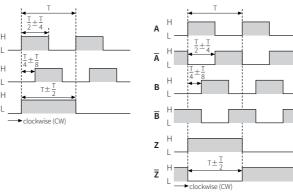


Output Waveform

- The rotation direction is based on facing the shaft, and it is clockwise (CW) when rotating to the right.
- Phase difference between A and B: $\frac{1}{4} \pm \frac{1}{8}$ (T = 1 cycle of A)

■ Totem pole / NPN open collector / Voltage output





Specifications

Model	E50S8-🗆-	E50S8-□- □-N-□-□	E50S8	E50S8		
Resolution	1/2/5 PPR ⁽¹⁾ 10 to 8,000 PPR model					
Control output	Totem pole output	NPN open collector output	Voltage output	Line driver output		
Output phase	A, B, Z	A, B, Z	A, B, Z	$A, \overline{A}, B, \overline{B}, Z, \overline{Z}$		
Inflow current	≤ 30 mA	≤ 30 mA	-	≤ 20 mA		
Residual voltage	≤ 0.4 VDC==	≤ 0.4 VDC==	≤ 0.4 VDC==	≤ 0.5 VDC==		
Outflow current	≤ 10 mA	-	≤ 10 mA	≤ -20 mA		
Output voltage (5 VDC==)	≥ (power supply -2.0) VDC=	-	-	≥ 2.5 VDC==		
Output voltage (12 - 24 VDC==)	≥ (power supply -3.0) VDC=	-	-	≥ (power supply -3.0) VDC==		
Response speed 02)	≤1µs ≤0.5 µs					
Max. response freq.	300 kHz					
Max. allowable revolution (33)	5,000 rpm					
Approval	C€ KEHE	CE KEIII	C € FR EHE	C € FR EHI		

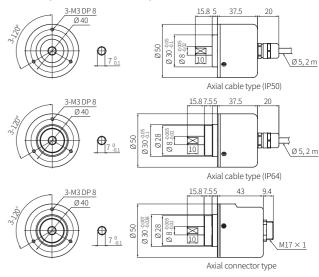
- tput, only A, B or A, A, B, B are outpu
- 02) Based on cable length: 2 m, I sink: 20 mA
- 03) Select resolution to satisfy Max. allowable revolution ≥ Max. response revolution [max. response revolution (rpm) = $\frac{\text{max. response frequency}}{\text{resolution}} \times 60 \text{ sec}$]

Connection	Axial cable type	Axial cable connector type	Axial connector type	Radial connector type		
Starting torque	≤ 0.007 N m		≤ 0.078 N m			
Inertia moment	$\leq 80 \mathrm{g} \cdot \mathrm{cm}^2 (8 \times 10^6 \mathrm{kg} \cdot \mathrm{m}^2)$		$\leq 400 \mathrm{g} \cdot \mathrm{cm}^2 (4 \times 10^{-5} \mathrm{kg} \cdot \mathrm{m}^2)$			
Allowable shaft load	Radial: ≤ 10 kgf, Thrust: ≤ 2.5 kgf					
Unit weight (packaged)	≈ 275 g (≈ 363 g)		≈ 180 g (≈ 268 g)			
	5 VDC== ± 5% (ri	nnla D D: < E0/4) /				
Power supply		5% (ripple P-P: $\leq 5\%$)	%) model			
Current consumption	Totempole, NPN open collector, Voltage output: ≤ 80 mA (no load) Line driver output: ≤ 50 mA (no load)					
Insulation resistance	≥ 100 MΩ (500 VDC== megger)					
Dielectric strength	Between the charging part and the case: 750 VAC \sim 50 / 60 Hz for 1 min.					
Vibration	1 mm double amplitude at frequency 10 to 55 Hz in each X, Y, Z direction for 2 hours					
Shock	≲ 75 G					
Ambient temp.	-10 to 70 °C, storage: -25 to 85 °C (no freezing or condensation)					
Ambient humi.	35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation)					
Protection rating	Axial cable type / cable connector type: IP50 (IEC standard) 01) Axial / Radial connector type: IP64 (IEC standard)					
Cable spec.	Ø 5 mm, 5-wire (Line driver output: 8-wire), shield cable cable type: 2 m, cable connector type: 250 mm					
Wire spec.	AWG24 (0.08 mm, 40-core), insulator diameter: Ø 1 mm					
Connector spec.	Totempole, NPN open collector, Voltage output: M17 6-pin plug type Line driver output: M17 9-pin plug type					

⁰¹⁾ Protection structure IP64 option is also available to order. (starting torque: ≤ 0.078 N m, inertia moment: ≤ 400 g·cm² (4 × 10⁻⁵ kg·m²))

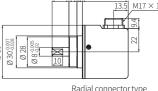
Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.
- Following items are based on cable type, connector type.
- Refer to 'Specifications' for detailed specifications of cable, wire and connector.

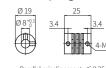




■ Bracket



■ Coupling



- Angular misalignment: ≤ 5°
 End-play: ≤ 0.5 mm

